Spectral Regularization for Max-margin Sequence Tagging

— Abstract —

- ► Max-margin learning of latent-variable sequence predictors
- Function class: Observable Operator Models
- ► Contributions:
 - * Max-margin completion of a Hankel matrix
 - * Spectral regularization for structured prediction
 - * Learning formulated as convex optimization

— Sequence Tagging —

hippopotamus

hIp-xpatxmxs

- ▶ Task Loss $\ell(\cdot, \cdot)$: Hamming distance
- Formulation using a scoring function

$$F: (\mathcal{X} \times \mathcal{Y})^* \to \mathbb{R}$$
$$\hat{y}(x) = \operatorname*{argmax}_{u \in \mathcal{V}^T} F(x, y)$$

► Max-margin Structured Prediction: given m training examples and a class of functions \mathfrak{F} solve

$$\underset{F \in \mathfrak{F}}{\operatorname{argmin}} \sum_{i=1}^{m} L(x^{i}, y^{i}; F) + \tau R(F)$$

- L(x, y; F) is the structured hinge loss $L(x, y; F) = \max \left[F(x, z) - F(x, y) + \ell(y, z)\right]$
- ightarrow R(F) is a regularization penalty for \mathfrak{F}

— Usual Function Classes —

► Factorized Linear Models of order k (e.g. CRF)

$$F(x,y) = \sum_{t=k+1}^{l} \mathbf{w} \cdot \mathbf{\Phi}(x,y_{t-k:t})$$

ightarrow tractable but very dependent on $\mathbf{\Phi}$ \leftarrow

► Latent-variable Models of order k (e.g. latent SVM, HCRF)

$$S(x, y, h) = \sum_{t=k+1}^{l} \mathbf{w} \cdot \mathbf{\Phi}(x, y_{t-k:t}, h_{t-k:t})$$
$$F(x, y) = \sum_{h} \exp\{S(x, y, h)\}$$

 \rightarrow intractable prediction and learning \leftarrow

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Ariadna Quattoni · · · Borja Balle ··· McGill University Xavier Carreras • • • Amir Globerson ··· The Hebrew University of Jerusalem — IO-OOM: Input-Output Observable Operator Models — — Prediction with IO-OOM — — Definition — $A = \langle \mathcal{X}, \mathcal{Y}, n, \boldsymbol{\alpha}, \{\mathbf{A}_{a,b}\}, \boldsymbol{\beta} \rangle$ Scoring function using h ▶ Alphabets: input \mathcal{X} , output \mathcal{Y} n states (i.e., hidden dimensions) S(x,▶ Initial weights $\boldsymbol{\alpha} \in \mathbb{R}^n$ ► Final weights $\beta \in \mathbb{R}^n$ Scoring function marginalizing h Operator for each bi-symbol $F(\chi$ $\mathbf{A}_{\sigma,\delta} \in \mathbb{R}^{n imes n} \quad \sigma \in \mathcal{X}, \delta \in \mathcal{Y}$ Global piecewise prediction of order k — Learning IO-OOM — • Regularizer: number of states n = |A|Piecewise objective argmin $\sum L(x^{i}, y^{i}; F_{k}) + \tau |A|$ $A \in \mathfrak{F}$ \rightarrow non-convex \leftarrow — The Hankel Matrix of IO-OOM — $\mathcal{X} =$ $H_{a,\heartsuit}$ $H_{\epsilon,\epsilon}$ $H_{a,\diamondsuit}$ $egin{array}{ccc} \mathbf{b} & \mathbf{c} & \mathbf{c} \ \heartsuit & \diamondsuit & \heartsuit \end{array}$ $\overset{a}{\heartsuit}$ $h_{\mathcal{S}}$

 $\mathbf{\Pi}_{\mathcal{P}}$

 $F_{k=3}(\underset{\heartsuit \oslash \oslash \oslash}{a \ a \ b \ c}) = F(\underset{\heartsuit \oslash \oslash}{c \ a \ a}) + F(\underset{\oslash \oslash \oslash}{a \ b \ c}) + F(\underset{\heartsuit \oslash \oslash}{a \ b \ c})$

▶ Definition: $\mathbf{H} \in \mathbb{R}^{\mathcal{P} \times \mathcal{S}}$ for A, using prefix-suffix sets $(\mathcal{P}, \mathcal{S})$ as basis, with: $\mathbf{H}((\mathfrak{u}, w), (v, z)) = F(\mathfrak{u}v, wz)$ ► The Fundamental Theorem of Weighted Automata (Schützenberger 1961; Carlyle & Paz 1971; Fliess 1974): F computed by A with n states \iff rank(H) \leq n for any basis (\mathcal{P}, \mathcal{S}) ► Main advantage: piecewise objective L is convex with respect to H

1. Obtain H optimizing L, via matrix completion techniques (Balle & Mohri 2012) 2. Recover A from H using the spectral method of (Hsu, Kakade & Zhang 2009) ► Method: 2a. Take the reduced SVD of $H_{\epsilon,\epsilon} = U\Sigma V^{\top}$ 2b. $\mathbf{A}_{\sigma,\delta} = (\mathbf{H}_{\epsilon,\epsilon}\mathbf{V})^+ \mathbf{H}_{\sigma,\delta}\mathbf{V}$; $\boldsymbol{\alpha}^\top = \mathbf{h}_{\mathcal{P}}^\top \mathbf{V}$; $\boldsymbol{\beta} = (\mathbf{H}_{\epsilon,\epsilon}\mathbf{V})^+ \mathbf{h}_{\mathcal{S}}$

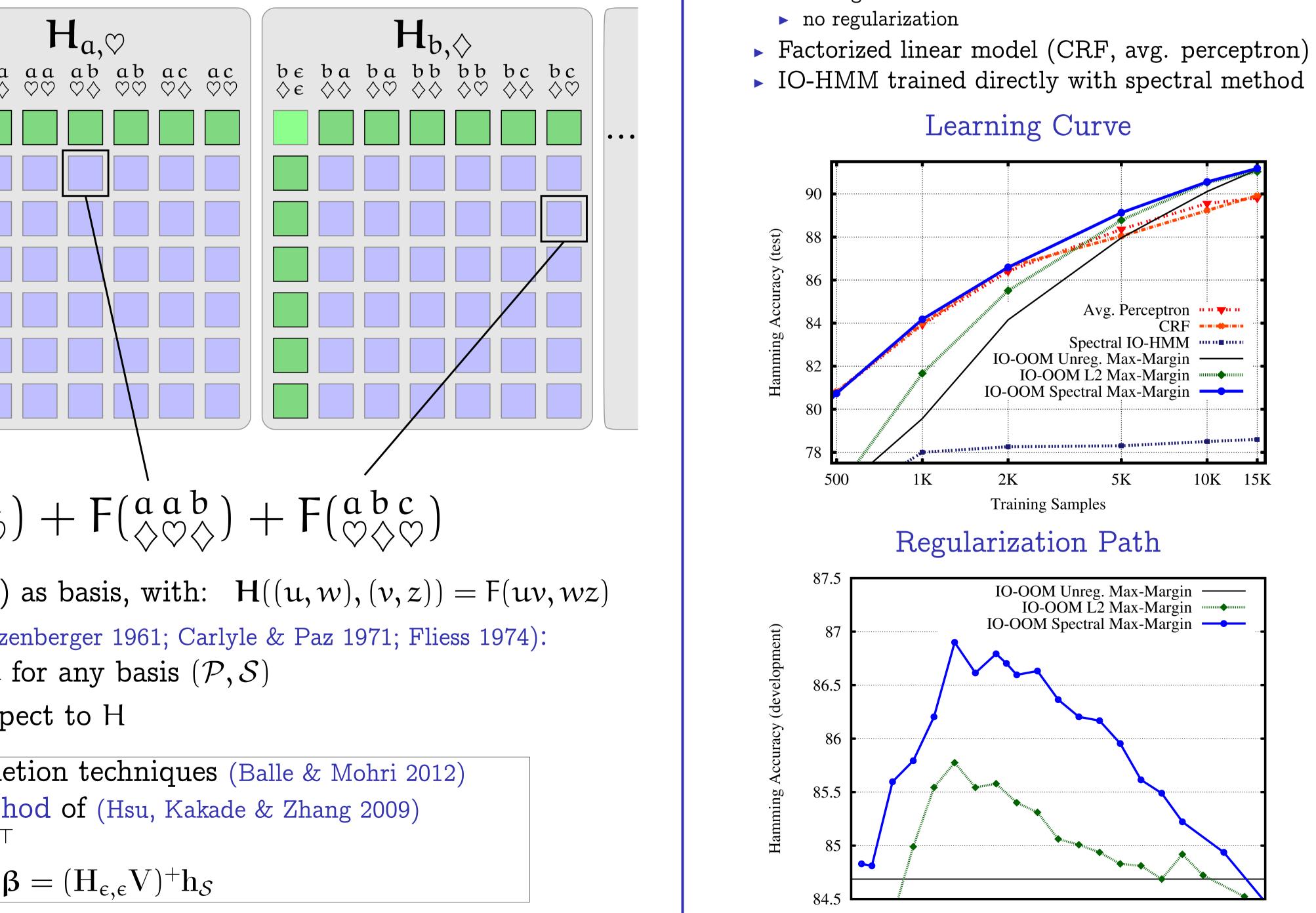
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$$(\mathbf{y}, \mathbf{h}) = \boldsymbol{\alpha}(\mathbf{h}_0) \left(\prod_{t=1}^T \mathbf{A}_{x_t, y_t}(\mathbf{h}_{t-1}, \mathbf{h}_t) \right) \boldsymbol{\beta}(\mathbf{h}_T)$$

$$(\mathbf{x},\mathbf{y}) = \sum_{\mathbf{h}} S(\mathbf{x},\mathbf{y},\mathbf{h}) = \boldsymbol{\alpha}^{\mathsf{T}} \mathbf{A}_{\mathbf{x}_{1},\mathbf{y}_{1}} \cdots \mathbf{A}_{\mathbf{x}_{\mathsf{T}},\mathbf{y}_{\mathsf{T}}} \boldsymbol{\beta}$$

$$\begin{split} \hat{f}_k(x) &= \operatorname*{argmax}_y \sum_{\substack{t=k+1 \ y}}^{l} F(x_{t-k:t}, y_{t-k:t}) \ &= \operatorname*{argmax}_y F_k(x, y) \end{split}$$

$$\{a, b, c\} \quad \mathcal{Y} = \{\diamondsuit, \heartsuit\}$$







— Convex Optimization —

Objective using Hankel and rank

$$\underset{\mathbf{H}\in\mathbb{H}(\mathcal{P},\mathcal{S})}{\operatorname{argmin}}\sum_{i=1}^{n}L(x^{i},y^{i};\mathbf{H})+\tau \operatorname{rank}(\mathbf{H})$$

$$ightarrow$$
 non-convex \leftarrow

Objective using Hankel and nuclear-norm

$$\begin{split} \hat{\mathbf{H}}_{S} &\in \underset{\mathbf{H} \in \mathbb{H}(\mathcal{P}, \mathcal{S})}{\operatorname{argmin}} \sum_{i=1}^{m} L(x^{i}, y^{i}; \mathbf{H}) + \tau \|\mathbf{H}\|_{*} \\ &\rightarrow \textit{convex} \leftarrow \end{split}$$

► We use Forward Backward Splitting (FOBOS) (Duchi & Singer 2011), based on gradient steps and proximal operators.

— Experiments —

Phonetic transcription, "Nettalk" data $(|\mathcal{X}| = 26, |\mathcal{Y}| = 51)$ (Sejnowski & Rosenberg, 1987) Methods compared:

- ► IO-OOM Max-margin with
- Spectral regularization
- ► L2 regularization